Autonomous Pick and Place System Assistive Robotics for Amazon Centers

Project

Amazon Robotics specializes in manufacturing leading technology for future Amazon operations. Due to rapid growth, Amazon is planning to expand by creating new centers all across the US. To support this exponential expansion rate, Amazon Robotics is augmenting their existing capabilities with robotic assistive systems.

Problem

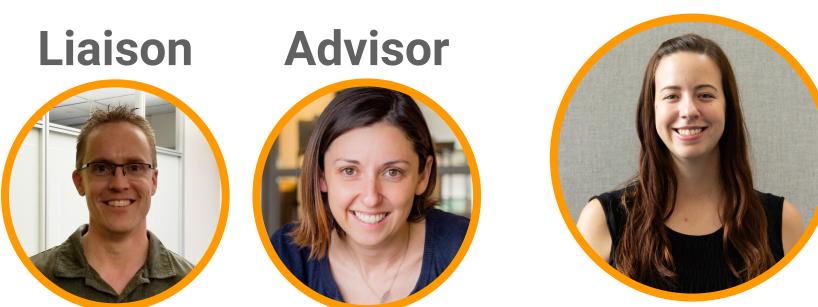
Our objective was to design an architecture capable of autonomously transferring items from a storage tote to an order tote with high reliability and eligibility. To facilitate these goals, our design specifications allow for use of additional packaging placed over items to simplify the pick and place operation. This system should be able to handle items of dimensions, weights, varying and characteristics.

Continuing SCOPE project into next

year

Large-scale trial implementation

at Amazon facility



Timothy Stallman

Identify

Our solution greatly simplifies the complex task of identifying the target item

Solution

Grasp

Our solution includes a handle to simplify handling the target item

Localize

Our solution makes the target item unique to simplify locating it

Sam Michalka

Anna Buchele



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Huang

Results

To help perform the "pick and place" of ordered items into shippable containers, our team has designed, built, and demonstrated an advanced pick and place robotic system that can move objects from storage to shipment more efficiently. The system has surpassed Amazon Robotics' minimum criteria and will be continued both as a SCOPE project and will have a trial implementation at an Amazon Robotics facility.

Normandeau

Wang

del Rio