Olingua Franca

Franklin W. Olin **College** of Engineering



A secure software architecture used to develop robust and smart distributed control systems

Controller

Data

Sensor

Our world is becoming **INSTRUMENTED**



Our world is becoming **INTERCONNECTED**

Virtually all things, processes and ways of working are becoming INTELLIGENT

Olingua Franca embodies these trends and creates a developerfriendly platform to securely interconnect control system components, bring high-order logic to low level systems, and create the virtual environment for a Smarter Planet



Controls Architecture

Olingua Franca breaks down all control systems into Controllers, Sensors, and Actuators. Each virtual component (represented by microchip icons) is connected to a physical device (a traffic light is one example).

Certified Components

All components within Olingua Franca must present cryptographically secure certificates to ensure a strong chain of trust

Controller

Controller

Secure Networks

Action to take

IPsec and Internet Key Exchange (IKEv2) are used to ensure network communication is secure. The API is also access controlled.

A traffic light is an example of an **ACUTATOR**

Actuator

Layered Control

High level commands & data

Higher level controllers (such as the one for a city) coordinate many lower-level subsystems (such as street intersections) by abstracting away low-level details. Imagine if traffic lights were aware of citywide trends such as rush hour.

Actuator

Broad Applicability

Traffic is only one example of an application of Olingua Franca. The architecture applies to the smart control of power, water, heating, or any similar system.

Resilient Systems

If components fail, Olingua Franca can automatically correct

The combined work of:

John Cohn | Lindsay Kaye | Jon McKay | Ryan Mitchell | Evan Morikawa | Alexander Morrow | Karl Schults | Kate Swift-Spong | John Watson Class of 2011 **IBM** Liaison Class of 2011 Class of 2013 Class of 2011 Class of 2011 Class of 2011 Class of 2011 Advisor